

NATIONAL BUREAU OF STANDARDS MICROCOPY RESOLUTION TEST CHART



PORTABLE DIAGNOSTIC RADIOMETER

FINAL REPORT - PHASE I
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PREPARED FOR

DEPARTMENT OF THE NAVY
NAVAL MEDICAL RESEARCH AND DEVELOPMENT COMMAND
NATIONAL NAVAL MEDICAL CENTER
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PREFACE

This Final Report for Phase I was prepared by RCA Laboratories, Princeton, New Jersey under Contract No. N00014-83-C-0524 for the Naval Medical Research and Development Command, Bethesda, Maryland. The work on Phase I was performed from October 1, 1983 through June 30, 1984 at the RCA Microwave Technology Center, Dr. Fred Sterzer, Director. The program was supervised by Markus Nowogrodzki, Head of the Microwave Subsystems and Special Projects Group. The Project Scientist was Robert W. Paglione, Member of the Technical Staff, with technical support provided by Francis J. Wozniak and Eugene C. McDermott.

The computer modeling and other software support was provided by Morris Ettenberg, Consultant.

I. INTRODUCTION

There exists a need for a portable diagnostic instrument that can noninvasively monitor and display internal body temperatures. This instrument would be extremely important on U.S. Navy ships whose complement does not include the services of competent medical professionals. In this case it would be important to determine whether a particular medical emergency does or does not exist in a patient. This would determine whether the patient should or should not be evacuated to a suitable medical facility for treatment.

The instrument would determine, by radiometric means, whether particular organs exhibit an elevated temperature. For example, this may be an aid in the diagnosis of appendicitis or nephritis.

The instrument described in this report is a dual-frequency microwave radiometer. The radiometer measures the amount of noise power being radiated from a localized tissue volume on the patient. The amplitude of this noise power over a frequency spectrum determined by the microwave components is proportional to the average temperature of the volume in question. Making this measurement at two separate frequencies can give an indication of the temperature profile over a depth as great as 6 cm.



II. TECHNICAL DISCUSSION

A. PROGRAM OBJECTIVE

The objective of Phase I of this program was to develop a "proof of concept" breadboard of a dual-frequency radiometer. The instrument should include a microprocessor, a readout, a power supply, and all circuits necessary to prove the concept of a self-balancing, multifrequency radiometer suitable for use as a diagnostic instrument by the U.S. Navy.

To meet this objective, the following tasks would be addressed:

- 1. Computer modeling of a multifrequency radiometer to determine the optimum frequencies that, when used with the portable radiometer, would provide temperature information at three body depths where hot-spots indicative of inflammation could be detected.
- 2. Adapting the self-balancing radiometer circuits to provide the multifrequency mode of operation determined from 1.
 - 3. Construction of a breadboard instrument model.
- 4. Evaluation and testing of the experimental instrument of 3.

B. COMPUTER MODELING

To be able to translate the multifrequency radiometric measurements of average temperature within a tissue volume into a three-point temperature profile, a computer model of the system and the resulting heat distributions as exhibited in particular radiometric measurements is required.

The computer program that has been developed calculates the

radiometric temperature at specified frequencies from a known temperature-versus-depth profile. The temperature profile is generated by assuming an arterial and ambient temperature and then calculating the heat transported due to the various heat conductivities and blood flows of the intervening tissue sections. The radiometric temperature is calculated in the following manner: The noise power, P_n , is calculated for a point on the temperature profile by multiplying the temperature, T_n , by Boltzmann's constant, k, and the receiver bandwidth, B. The amount of this power that reaches the surface is found by assuming an exponential decay with distance — the exponential constant being the attenuation constant, , of the intervening tissues. The radiometric temperature is then the sum of all of the surface noise powers generated by all of the points on the profile divided by kB. Mathematically this is written as

1)
$$T_{RAD} = T_1 \left\{ 1 - \exp(-\alpha_1 x_1) \right\} + T_2 \left\{ 1 - \exp(-\alpha_2 x_2) \right\} \exp(-\alpha_1 x_1) + T_3 \left\{ 1 - \exp(-\alpha_3 x_3) \right\} \exp\left\{ -(\alpha_1 x_1 + \alpha_2 x_2) \right\} + \dots + T_n \left\{ 1 - \exp(-\alpha_n x_n) \right\} \exp\left\{ -\alpha_1 x_1 + \alpha_2 x_2 \right\} + \dots + \alpha_2 x_2 + \dots + \alpha_{n-1} x_{n-1} \right\}$$

where n = number of tissue sections

x = thickness of tissue section

and α = attenuation constant of tissue section.

The curve in Fig. 1 was generated by using the computer model and by assuming an arterial temperature of 37°C and an ambient temperature of 21°C. The tissue geometry used was taken from a body slice in the area of the appendix. This slice,

shown in Fig. 2, contains skin, fat, muscle, intestine, the appendix (processus vermiformis), and bone. The front-to-back tissue thicknesses used in the model are: lmm-skin, 8.5mm-fat, 6.55cm-intestine, lcm-appendix, 3.3cm-muscle, 5.lcm-bone, 1.4cm-muscle, 1.05cm-fat, and 6.5mm-skin. Typical values were used for the tissue density, thermal conductivity, specific heat, and blood flow. Also, a value was used for normal surface cooling. The curve in Fig. 1 is therefore a normal thermal profile in the appendix region. The radiometric temperature was calculated over the frequency range from 800 to 4000 MHz. The front surface reading is labeled TF(rad) in the figure, and only the 800 and 4000 MHz data are shown since the temperature function is linear between these two points.

In Fig. 3a, b, and c, the appendix has been given an elevated temperature of 2° over normal; and the position of the appendix is varied from 4 to 8 cm. It can be seen from this data and the data in Fig. 1 that the radiometer must have an accuracy of 0.2°C in order to detect a 2°C elevated temperature at a depth of 6 cm.

In Fig. 4 and 5, the radiometric temperatures at 800 and 4000 MHz are plotted as a function of the surface temperature and hot-spot depth. The line representing no hot spot (NHS) is also shown in both figures. Therefore, from the measurement of the surface temperature and the radiometric temperature at 800 and 4000 MHz, it is possible to determine the depth of a typical hot spot. The temperature profile can then be extracted from the computer model. For example, if the surface and radiometric

temperatures are 33.7°C, 36.7°C at 800 MHz, and 36.1°C at 4000 MHz; then the hot spot occurs at a depth of 4 cm. The temperature profile for this condition is as shown in Fig. 2b; and the three temperatures that would be displayed are 34.7°C at 0 cm depth, 37°C at 2 cm depth, and 38.7° at 4 cm depth.

C. 4 GHz SUBSYSTEM

The basic Dicke-type radiometer is shown schematically in Fig. 6. In this circuit, the target noise power entering through the antenna is compared to the noise power eminating from a temperature-controlled termination. The difference between the two signal levels is displayed on the DC meter--this reading is proportional to the temperature of the target. An improvement can be made in the accuracy of this system if the reference noise signal, in this case the oven-controlled termination, was always adjusted to give a zero reading on the DC meter; then the temperature of the reference noise source would be equal to the temperature of the target. This self-balancing scheme can be realized by replacing the over-controlled termination with a diode noise source. The mixer can also be replaced with a synchronous detector to improve the system sensitivity and reduce the system noise.

The single-throw-double-pole switch is usually realized with an electronically-switched, latching ferrite circulator; however, at these frequencies, the size, weight and current drawn by these components are limiting factors when considering a portable instrument. The switch can also be designed using switched low-noise amplifiers, as shown in Fig. 7. Each amplifier is pulsed

on and off asynchronously with the other, and the off-channel isolation is greater than 40 dB. The output of each amplifier is combined through a 3 dB hybrid coupler to produce a single switched output.

The amplifiers were designed around the NE13783-4 field-effect transistor--these transistors are optimized for low-noise performance at 4 GHz. The scattering parameters of these devices were measured with a computer-controlled automatic network analyzer. Input and output matching networks were designed that would produce an amplifier with a minimum gain of 13 dB from 3.7 to 4.2 GHz. The amplifiers were assembled on pallets and tested. A photograph of an amplifier pallet is shown in Fig. 8 and the measured gain of a typical amplifier is shown in Fig. 9. The assembled switch and amplifier are shown in the photographs of Figs. 10 and 11. The gain of the 3-stage amplifier with isolators is shown in Fig. 12.

D. 800 MHz SUBSYSTEM

The 800 MHz amplifier and switch were designed in a similar manner as the 4 GHz amplifiers. The solid-state devices used in this case were AT-41470 low-noise bipolar transistors. A photograph of the switch and amplifier is shown in Fig. 13 and 14. The gain response of the 2-stage amplifier is shown in Fig. 15.

E. ANTENNAS

Folded-dipole antennas were chosen for the radiometer since they can easily be made on a printed-circuit board, they can be made balanced, and they operate over a wide bandwidth. 5 A

photograph of the 800 and 4000 MHz antenna assembly is shown in Fig. 16. Each antenna on the antenna board, also shown in Fig. 16, is connected to a 3.6mm coaxial line that protrudes out the back of the drawn-aluminum housing. The antenna board is mounted within the housing at a distance of 1.6mm from the open end. The 1.6mm gap is filled with a layer of neoprene rubber foam that acts as a thermal insulator. A 300K-ohm thermistor (Victory Engineering, Model 53A55) is epoxied into the antenna board so that it protrudes slightly through the foam rubber to contact the tissues being measured. The thermistor wires also come out the back of the aluminum housing.

The back of the aluminum housing also acts as the reflecting backplane for the 800 MHz antenna; a brass plate (38.1mm wide x 16.5mm high x 0.8mm thick) mounted on the coaxial line of the 4 GHz antenna at a distance of 10 cm from the rear of the antenna board acts as its reflecting backplane.

The VSWR of these antennas measured while the assembly is in contact with tissue is shown in Fig. 17.

F. LOW-FREQUENCY COMPONENTS

The schematic for the dual-frequency radiometer, including the low-frequency and digital components, is shown in Fig. 18. the low-frequency components consist of a 100 Hz modulator, a filter/amplifier, a synchronous detector and loop amplifier, a pulse-width modulator, and a switching regulator.

A photograph of the 100 Hz modulator and its associated schematic are shown in Figs. 19 and 20. This circuit produces a 200 Hz, crystal-controlled square-wave that is divided by a flip-

flop to achieve a 100 Hz modulation frequency. IC3 and Q5, and IC4 and Q6 produce 10 V pulses capable of driving 20 ma to the collector of each bipolar amplifier stage in the 800 MHz switch. Q3 and Q4 provide the same function for the 4000 MHz switch with 3 V pulses driving 10 ma to the drains of the FET amplifiers. Q1 and Q2 provide a slow-turn-on 3.6 V supply for Q3 and Q4.

The filter/amplifier is shown in the photograph of Fig. 21 and schematically in Fig. 22. All ICs are OP-27 low-noise operational amplifiers. The first stage is a buffer stage that provides AC coupling, transient protection, and a DC return path for the active filter. The second stage is the active filter with a gain and cutoff frequency of approximately 3 dB and 1 KHz.

The third stage is a variable-gain amplifier that provides 0 to 40 dB of gain. The filter response at full gain for the entire circuit is shown in Fig. 23.

The photograph and schematic for the synchronous detector and loop amplifier are shown in Figs. 24 and 25. The synchronous detector is built around the AD630 balanced modulator/demodulator chip, connected as an in-phase detector. In this mode the AD630 will produce a DC output voltage that is proportional to the difference between the two input signals when the two input signals are in phase with the reference signal, which in this case is the 100 Hz modulation to the switches. Therefore, any system noise that has been impressed on either or both inputs is greatly reduced and the overall detection sensitivity is greatly increased.

IC3 in Fig. 25 is the loop amplifier. The amplifier is an

integrator with a time constant of approximately 3 seconds. The op-amp is connected in the inverting mode so that when the input voltage goes negative (this is indicative of an increasing target temperature), the output goes positive. A change in the output voltage of the loop amplifier causes a change in the noise power out of the noise diode which in turn brings the input voltage to zero or into a balanced loop condition.

The pulse-width modulator board is shown in the photograph of Fig. 26 and schematically in Fig. 27. The CA1524 outputs 28 V pulses at a 1 KHz repetition rate to the diode noise source. The pulse width of these pulses varies between 0 and 100% as the control voltage varies between 1 and 3.5 V. The DC average of these pulses is proportional to the target temperature, and it is this voltage that is read by the microprocessor and converted into temperature.

Most of the DC voltages required by the various components in the radiometer system are supplied by the switching regulator shown in the photograph of Fig. 28 and the schematic of Fig. 29. The power supply was designed to operate with a +12 VDC input which would be supplied by a rechargeable battery in Phase II. The FET bias voltages, that is the -5 V gate supply and +3 V drain supply, are sequenced such that on turn-on the gate voltage is on before the drain voltage and on turn-off the gate is off after the drain voltage. The turn-on and turn-off sequencing can be seen in the oscillographs of Fig. 30a and b.

G. DIGITAL PROCESSOR SUBSYSTEM

The digital processor subsystem is shown in the photograph

FIGURE CAPTIONS

- Fig. 1. Temperature-versus-depth profile in tissue calculated using assumed arterial and ambient temperatures of 37 and 21°C. The tissue geometry is that of a body slice in the area of the appendix. TF(rad) is the radiometric temperature measured at a depth of 0 cm.
- Fig. 2. A 2.5 cm thick body slice in the area of the appendix (12 Processus vermiformis).
- Fig. 3. Temperature profile in tissue calculated using assumed arterial and ambient temperatures of 37 and 21°C. An elevated temperature of 2°C, representing an inflamed appendix, is calculated for depths of (a) 4 cm, (b) 6 cm, and (c) 8 cm.
- Fig. 4. The calculated radiometric temperature as a function of surface temperature and hot-spot depth for an 800 MHz radiometer.
- Fig. 5. The calculated radiometric temperature as a function of surface temperature and hot-spot depth for a 4 GHz radiometer.
- Fig. 6. Basic Dicke radiometer schematic.
- Fig. 7. Schematic of a single-pole-double-throw (SPDT) micro-wave switch using low-noise amplifiers.
- Fig. 8. Photograph of the NE13783-4 low-noise amplifier pallet.
- Fig. 9. Measured gain of a typical NE13783-4 amplifier pallet.
- Fig. 10. Photograph of the assembled FET SPDT switch.

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288 0152 6D			INF	5	
289 0153 17			INC	RZ	
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291 0155 6E			INF	6	
292 0156 27 293 0157 57			DEC	RZ	
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295 015A 26			DEC DEC	OF2H R6	DIVIDE REMAINDER BY 10 (OPH)
296 015B 56			SIR	R6	
297 015C 07			LIM	R7	
298 015D 26			DEC	R6	
299 015E 56			STR	R6	
300 015F F80A			LDI	OAH	
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303 0163 F8FC			STR LDI	R6	
304 0165 26			DEC	OFCH R6	
305 0166 56			STR	R6	
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00146 00AE F1		OR		
00147 00AF FBF	F	XRI	OFFH	; COMPLEMENT LS BYTE
00148 00B1 27		DEC	RZ	
00149 00B2 57		STR	R7	
00150 00B3 17		INC IRX	R7	
00151 0084 60 00152 0085 F0		LTIX TKX		
00132 00B3 F0		SHR		
00154 00B7 F6		SHR		
00155 00B8 F6		SHR		
00156 00B9 F6		SHR		A company of the comp
00157 00BA FBF		XRI	OFFH	COMPLEMENT MS BYTE
00158 00BC FAC)F	ANI	OFH C/2	MASK DUL WE BITS
00159 00BE 57		STR	R7	

and the second s

CENTRONIX	1802 ASM V3.3		P'AGE 2
00054 0048 F801 00055 004A 55 00056 004B F812 00057 004B 53		LDI 01H STR R5 LDI 12H STR R3	
00 058 000 59 004E 7A	***RFGIN	MEASUREMENT L REQ	JOUP JSET RF SWITCHES TO 46HZ
00060 004F F801		LDI 01H	SET RETURN ADDRESS
00061 0051 BE		PHI RE	
00062 0052 F8DE 00063 0054 AE		LDI ODEH FLO RE	
00064 0055 DE		SEP RE	;CALL DELAY SUBR.
J00 65	;**		
00066 0056 F84F	LF1	LDI 4FH	FENABLE CDF1851
00067 0058 26 00068 0059 56		DEC R6 STR R6	SET FORT B TO INPUT SET FORT A TO OUTFUT
00069 005A F833		LUI 33H	
00070 0050 26		DEC R6	
00071 005D 56		STR R6	
00072 005E F808 00073 0060 26		LDI 08H DEC k6	
00074 0061 56		STR R6	
000 75 0062 61		OUT 1	
00076 0063 62		001 2	
00 077 0064 62 00078	;* *	OUT 2	
00079 0065 F600	ייזייתינ	LDI OOH	FINITIALIZE STACK TO O
პმპი 0067 26		DEC R6	
00081 0068 56		STR R6	
00082 0069 26 00083 006A 56		DEC R6 STR R6	
00084 006B F810		LDI 10H	;INITIALIZE R8 TO 16
00085 006D 58		STR R8	
00086	# *	•	
00087 006E 0C 00088 006F FF10	AVG	LDN RC SMI 10H	FSET CD4066 INFU[MUX TG FINFU] CHANNEL 1 OR 2;
00089 0071 26		DEC K6	#GIVE A-TO-D CONVERT COMMAND,
პპმ ში 0072 56		STR R6	FRESET CD4013 TOGGLE FF
00091 0073 0C		LIN RC	GIVE TOGGLE COMMAND TO
00092 0074 26 00093 0075 56		DEC R6 STR R6	#CD4013 TOGGLE FF
00073 0073 38 00094 0076 08		LDN RB	
პმ 095 მმ77 26		DEC R6	
00096 0078 56		STR R6	
00 097 0079 0A 00 098 007A 26		LUN RA DEC R6	
00099 007B 56		DEC R6 STR R6	
00100 007C 64		υυ ι 4	
00101 007D 64		OUT 4	
00102 007E 64		001 4	
00103 007F 64 00104	j**	OUT 4	
001 05 0080 26		DEC R6	#INPUT A-TO-D BITS 5.6.7.8.1.2.3.4
00106 0081 6E		INF 6	;[MSB=BIT 1, LSB=BIT 12]

FERTRONIX	1802 ASM V3.3	PAGE 1
000 01	;**INITIALIZE REG	
00002 0000 F84F		4FH JSET MS BYTE OF RAM TO 4FH
00003 0002 83	PHI	R3
00004 00 03 84 0000 5 0004 B5	FHI PHI	R4
00005 0004 85	FHI	ጽ5 ጽ6
00007 0006 B7		
00000 0000 B7	FHI	K7
00008 0007 BB	PHI PHI	R8 R9
00007 0008 B7	PHI	KA
00010 0007 BA	FHI	RB
00011 000H BB	PHI	RU
00012 0000 BD	PHI	RD
00013 0000 BB	FHI	RF
00014 000B BF	LDI	80H
00016 0010 A6	PLO	R6
00013 0010 Ha	SEX	R6 #SET STACK TO R6
00017 0011 E8 00018 0012 F810	LDI	10H #R7 ADDRESS=4F10H << FEMF. DATA>>
00019 0014 A7	PLO	R7
00020 0015 F800	LDI	OOH ;R8 ADDRESS=4FOOH < <avg. cntr.="" loup="">></avg.>
00021 0017 A8	PLO	R8
00022 0018 F820	LDI	20H ;RA ADDRESS=4F20H << MUX CHAL CUMMAND>.
00023 001A AA	PLO	RA
00024 001B F830	LDI	30H FRB ADDRESS=4F30H << CONVERT COMMAND>>
00025 001D AB	PLO	RB
00026 001E F840	LDI	40H :98 ADDRESS=4F40H << TOGGLE COMMANDO>>
00027 0020 AC	PLO	RC
00028 0021 F850	LUI	50H JRD AUDRESS=4F50H < <main chtr="" loop="">></main>
00029 0023 AD	PLO	RD
00030 0024 F860	LUI	60H JRF ADDRESS=4F60H < $>$
00031 0026 AF	FLO	RF
000 32 0027 F861	LDI	61H FR9 ADURESS=4F61H < $>$
00033 0029 A9	PLO	R9
00034 002A F862	LBI	62H JRS ADDRESS=4F62H < $>$
00035 002C AS	PLO	R5
00036 002D F863	LDI	63H FR4 ADDRESS=4F63H < $>$
00037 002F A4	PLO	R4
00038 0030 F864	LDI	64H FR3 ADDRESS=4F64H < <mail constant="">></mail>
00039 0032 A3	PLO	R3
00040 0033 F800	LDI	OOH FINITIALIZE RA TO MUX CHAL 1
00041 0035 5A	STR	RA
00042 0036 F880	LDI	80H ;INITIALIZE CUNVERT COMMAND
00043 0038 5B	STR	RB
00044 0039 F810	LDI	10H ;INITIALIZE TOGGLE COMMAND
00045 003B 5C	STR	RC - 03H -
00046 003C F803 00047 003E 5D	LDI	
00048 003F F807	STR LDI	RD 07H
00048 003F F807	STR	RF
00050 0041 SF	LDI	9EH
00050 0042 7872	STR	72A R9
00051 0044 57 00052 0045 F810	LDI	10H
00052 0043 7510	STR	R4
22000 0047 04	311	15.7

J. PLANS FOR PHASE-II

The prototype unit will be delivered under Phase II of the program. A photograph of the shell of the planned prototype is shown in Fig. 38. Not shown in the photograph is the 12 volt, 3 amp-hour battery and charger unit that will connect to the pistol grip.

The display on the rear panel of the unit is a 16-character liquid-crystal display that will simultaneously display the three temperatures corresponding to the temperature of the surface and the temperature at two depths.

	4 GHz HEX (Decimal)	800 MHz HEX (Decimal)	Thermistor HEX (Decimal)
Cl	64 (100)	64 (100)	64 (100)
C2	959 (2393)	A77 (2679)	BF5 (3100)
C3	73 (115)	BE (190)	F1 (241)
C4	140 (320)	140 (320)	12B (299)

For the above constants, the 800 MHz radiometer will resolve temperatures between 18.5 and 45.4°C; the 4 GHz radiometer between 9.8 and 54.1°C; and the thermistor between 19.3 and 40.4°C.

I. RADIOMETER EVALUATION

Next Significant Digit (NSD) = $\frac{R1}{10}$ = D2+R2

Least Significant Digit (LSD) = R2.

D1, D2 and R2 are then displayed on the liquid crystal display.

The Q lines are next set to switch the latching switches into the 800 MHz position; and, with different constants in eqn. 2, a new temperature is measured and displayed. Finally the surface thermistor is interfaced to the A-to-D through a buffer amplifier and the multiplexer, and the surface temperature is calculated and displayed in a similar manner. The flow chart for the above sequence is shown in Fig. 36.

The source file that contains the assembly code for the radiometer system is listed in Appendix A.

H. BREADBOARD

The breadboard unit is shown in Fig. 37. The unit was calibrated by placing the antenna in contact with saline that was maintained at various temperatures. The antenna housing was covered with a thin layer of plastic food wrap for the calibration procedure. The saline was contained in a galvanized steel pail whose inside surfaces were lined with a 1/4 inch thick carbon-impregnated foam material. The lossy foam essentially makes the pail of saline appear as an infinite volume at a known temperature.

The radiometer and therristor voltages were recorded for saline temperatures of 24 and 40°C. The constants of the linearizing equation (eqn. 2) are:

of Fig. 31. It consists of a power supply (±15 V and +5 V), a CDP18S601 microboard computer, a multiply/divide unit, and an interface and display board.

The CDP18S601 card contains a CDP1802 CPU, a 2 MHz crystal-controlled clock, read-write memory, parallel I/O ports, and sockets for up to 8 kilobytes of EPROM. The layout of the major components on this card is shown in Fig. 32. The CDP1855 multiply/divide unit is located between the CDP18S601 and the interface card. The schematic for this device is shown in Fig. 33. The schematic for the interface and display card is shown in Fig. 34, and the respective card interconnection diagram is shown in Fig. 35.

The subsystem operation is basically as follows: On start-up, the CPU resets the Q line (P1-6) which sets the latching switches (see Fig. 18) to the 4 GHz radiometer position. The radiometer output voltage is connected to the 12-bit A-to-D converter on the interface card through a buffer amplifier and the input multiplexer. The CPU converts the 12-bit digital code into a temperature using

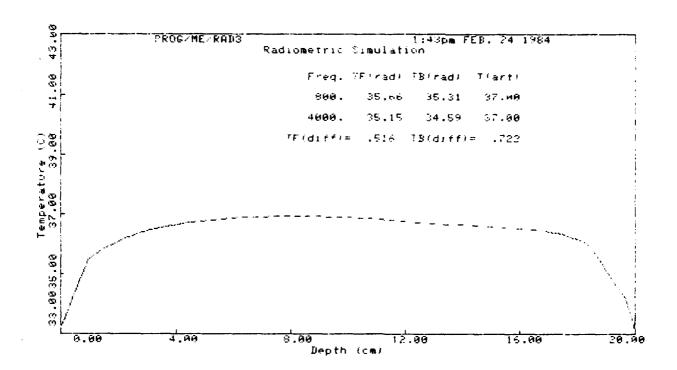
2)
$$T = \frac{C1*(N-C2)}{C3} + C4$$

where N=12-bit digital number in hexadecimal and Cl through C4 are constants. The temperature, T, calculated in eqn. 2 is in hexadecimal and must be converted to decimal digits for display. This is accomplished by using the following

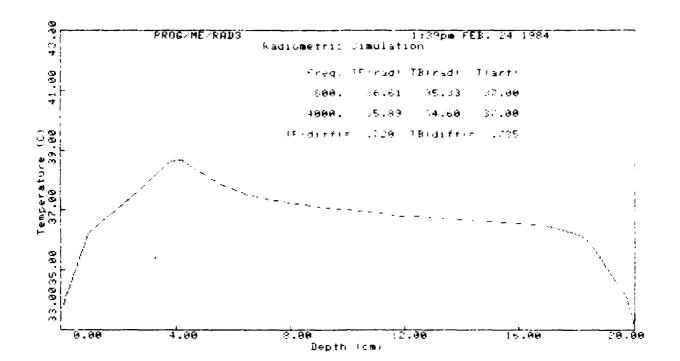
3) Most Significant Digit (MSD) = $\frac{T}{100}$ = DIGIT 1(D1)+Remainder 1 (R1)

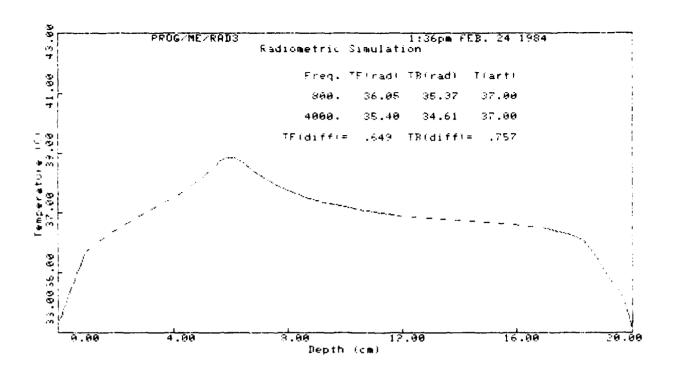
- Fig. 11. Photograph of the 3-stage FET amplifier.
- Fig. 12. Measured gain response of the 3-stage FET amplifier.
- Fig. 13. Photograph of the AT-41470 SPDT switch.
- Fig. 14. Photograph of the 2-stage AT-41470 amplifier.
- Fig. 15. Measured gain response of the 2-stage AT-41470 amplifier.
- Fig. 16. Photograph of the dual-frequency antenna assembly.

 The printed circuit board with the 800 and 4000 MHz antennas is shown in the foreground.
- Fig. 17. a) VSWR of the 800 MHz antenna measured with the antenna in contact with body tissue; b) the same for the 4 GHz antenna.
- Fig. 18. Schematic representation of the dual-frequency radiometer.
- Fig. 19. Photograph of the 100 Hz modulator board.
- Fig. 20. Schematic diagram for the 100 Hz modulator.
- Fig. 21. Photograph of the 1 KHz filter/amplifier.
- Fig. 22. Schematic diagram for the 1 KHz filter/amplifier.
- Fig. 23. The gain response of the filter/amplifier as a function of frequency. (The gain is adjusted for a maximum.)
- Fig. 24. Photograph of the synchronous detector and loop amplifier board.
- Fig. 25. Schematic diagram for the synchronous detector and loop amplifier.
- Fig. 26. Photograph of the pulse-width modulator board.
- Fig. 27. Schematic diagram for the pulse-width modulator.
- Fig. 28. Photograph of the switching regulator.
- Fig. 29. Schematic diagram for the switching regulator.

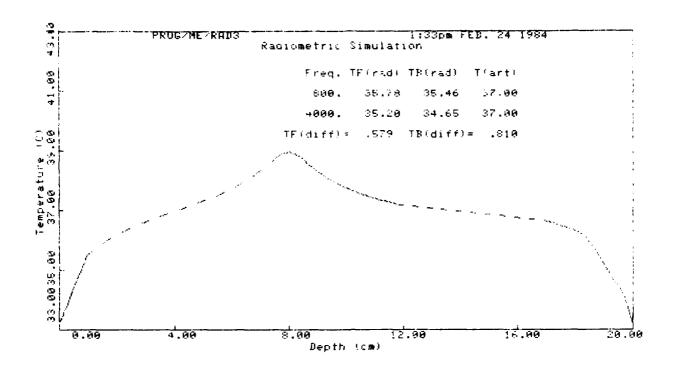


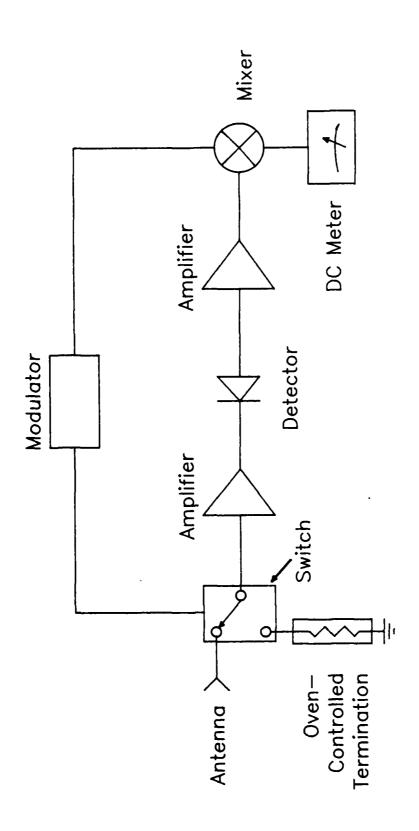
SECTION 38

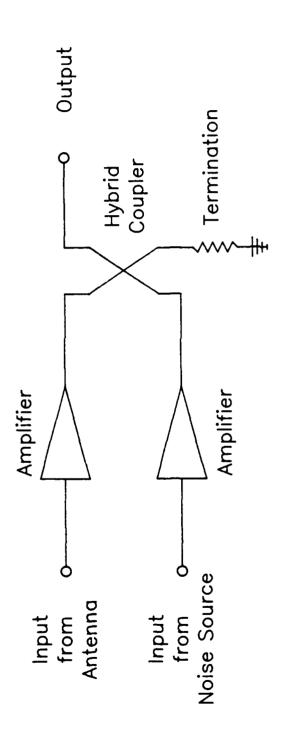


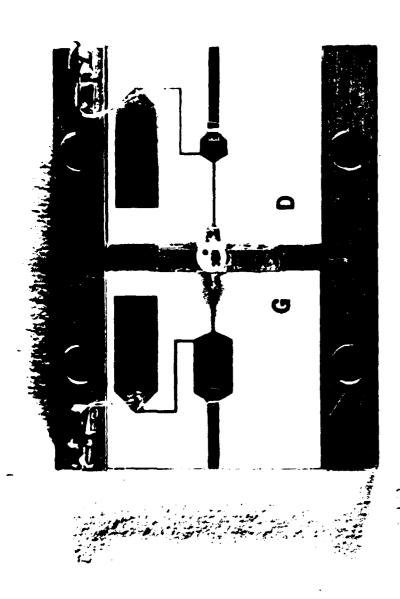


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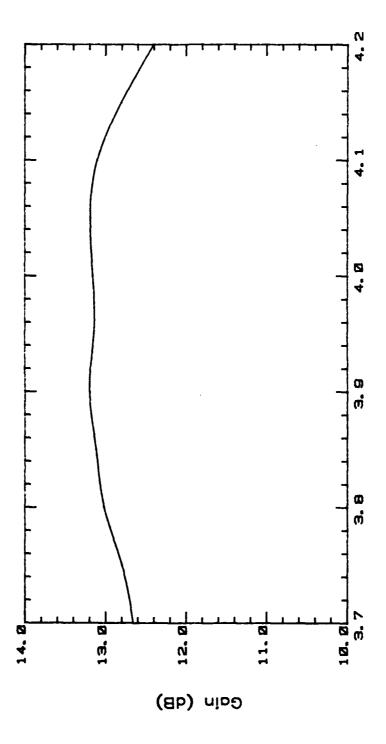




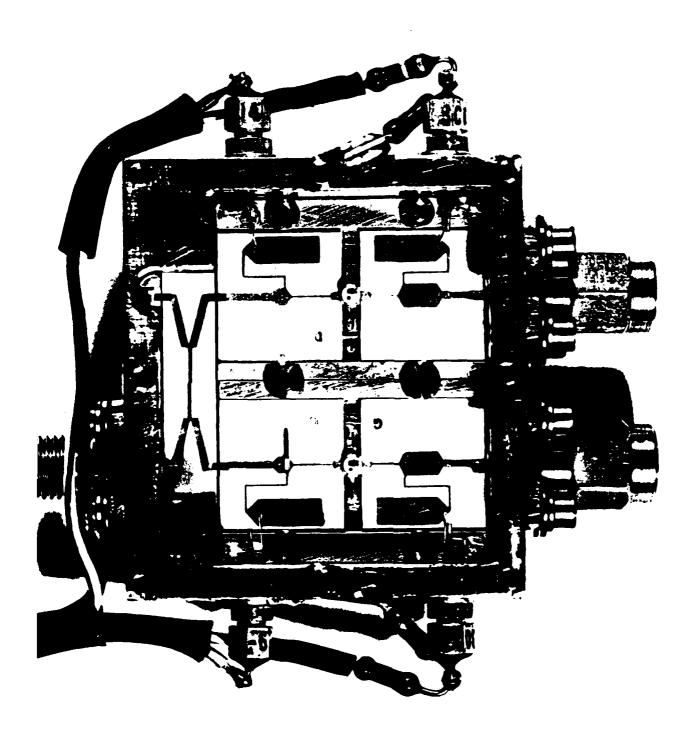




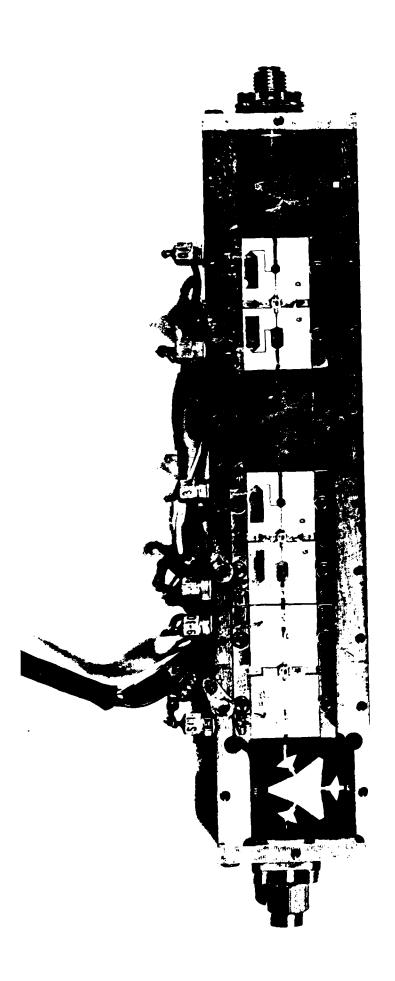




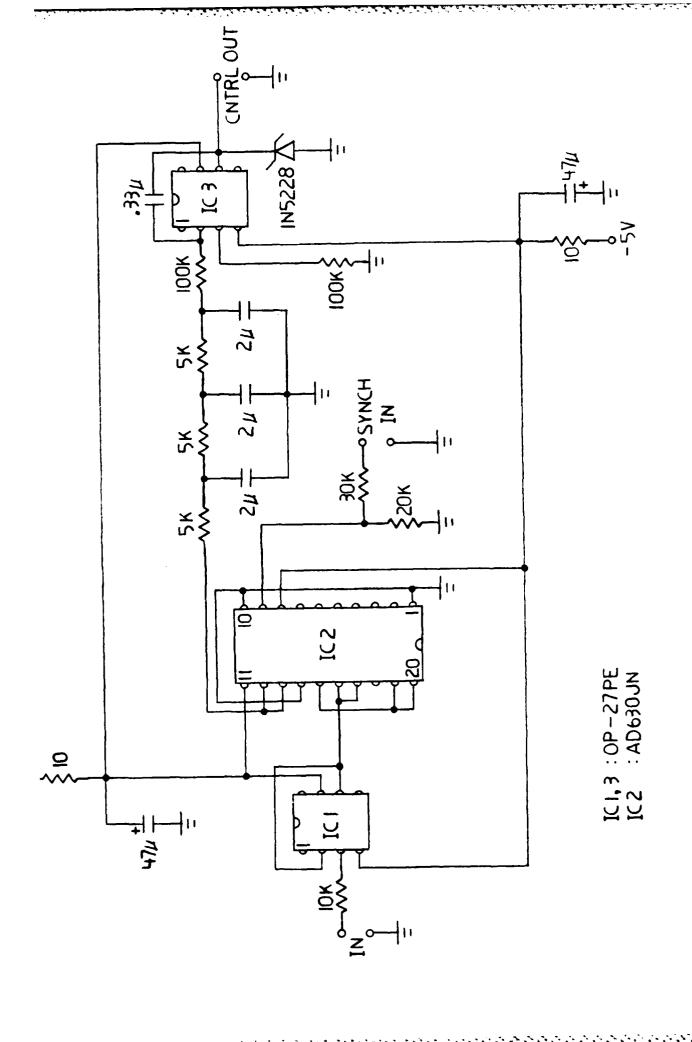
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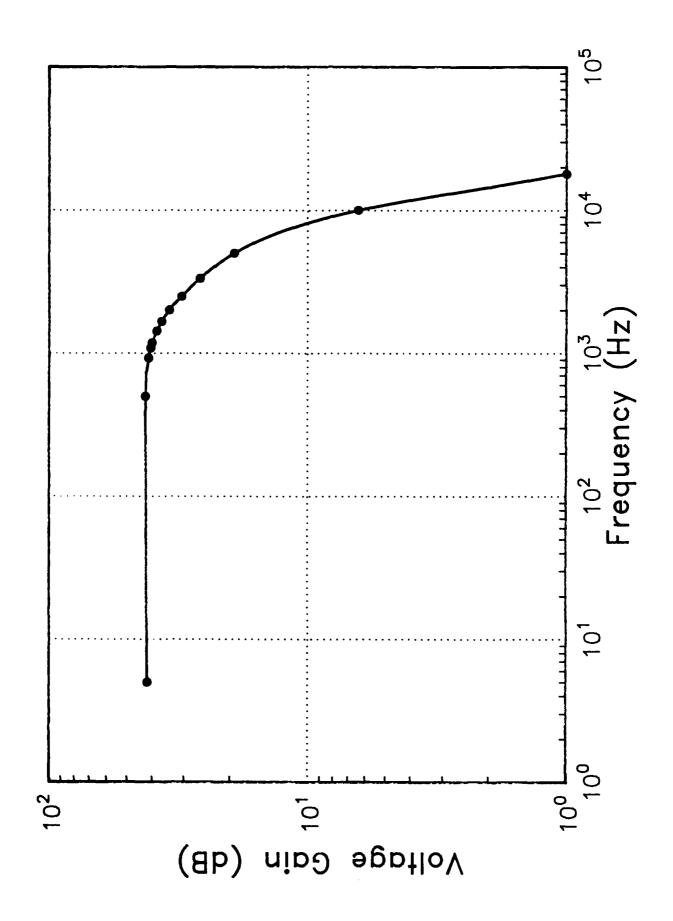
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CM

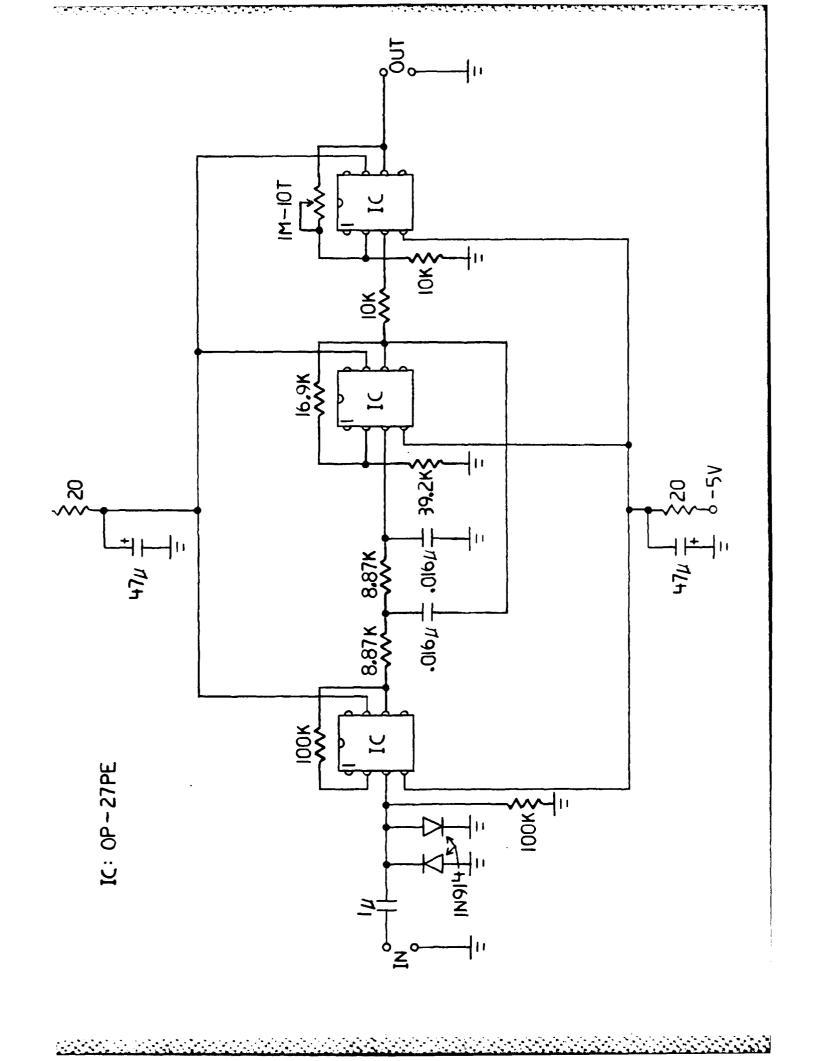


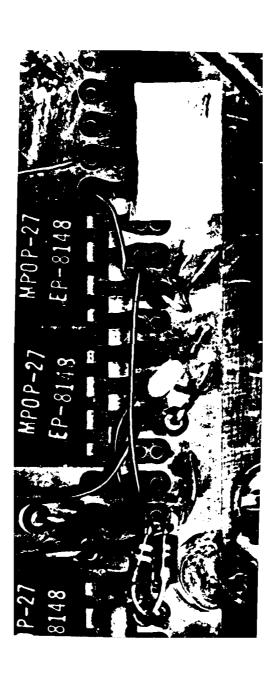


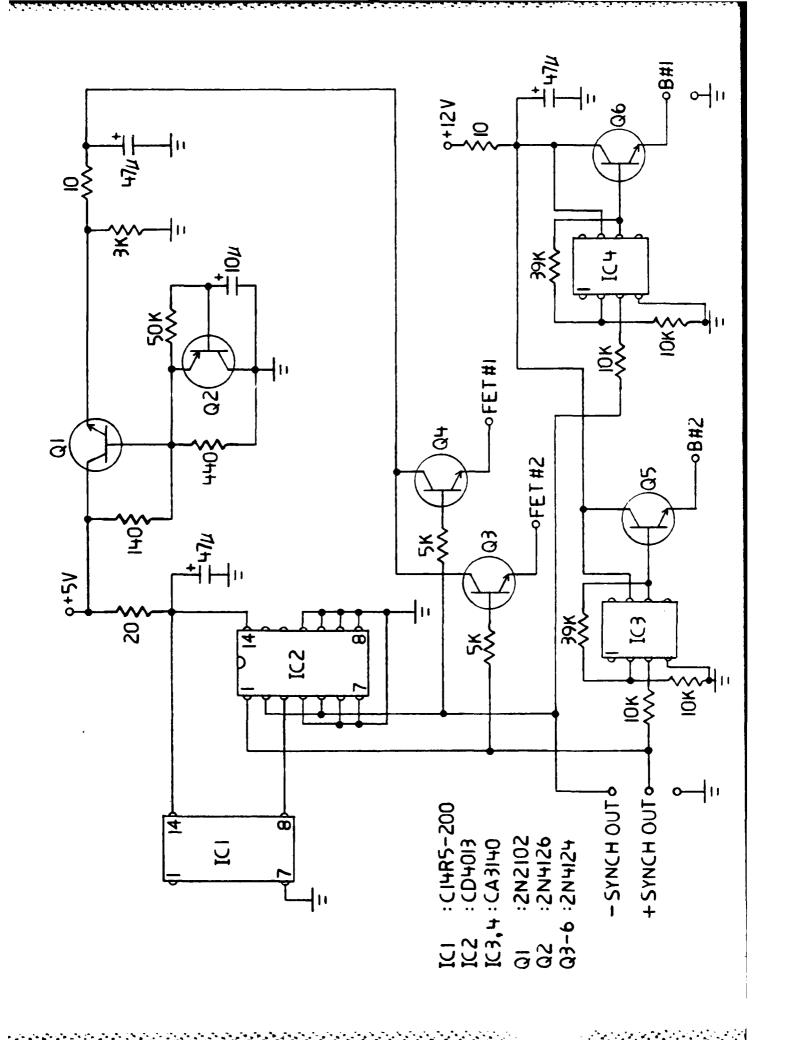


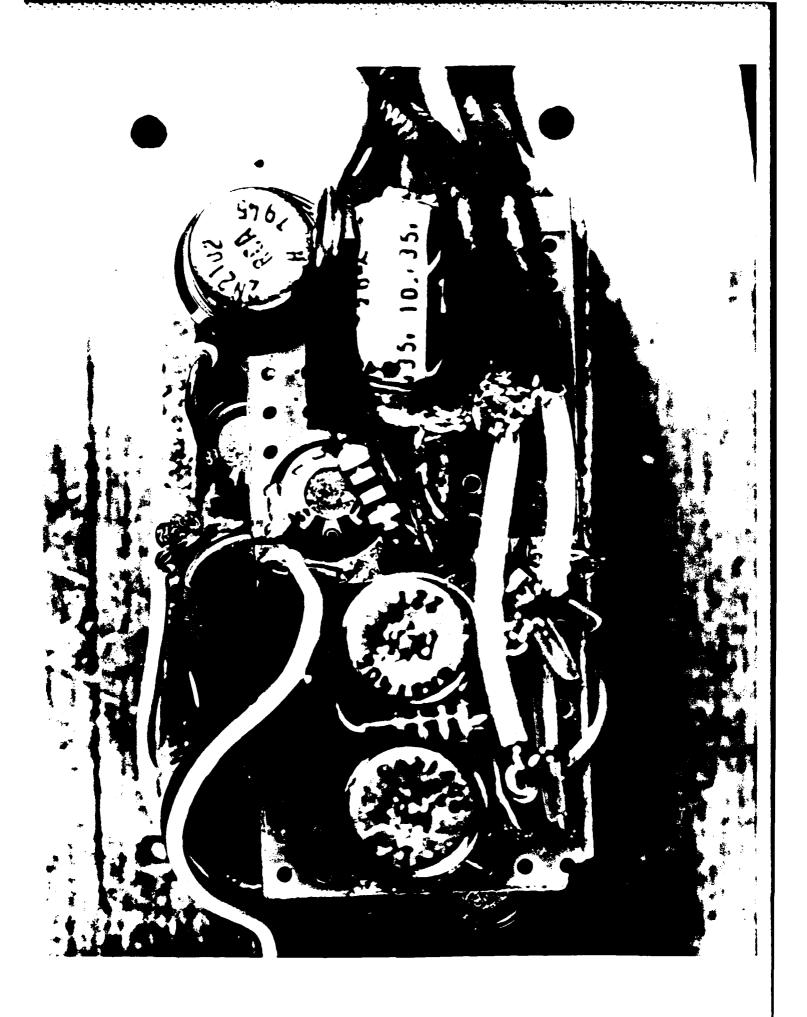


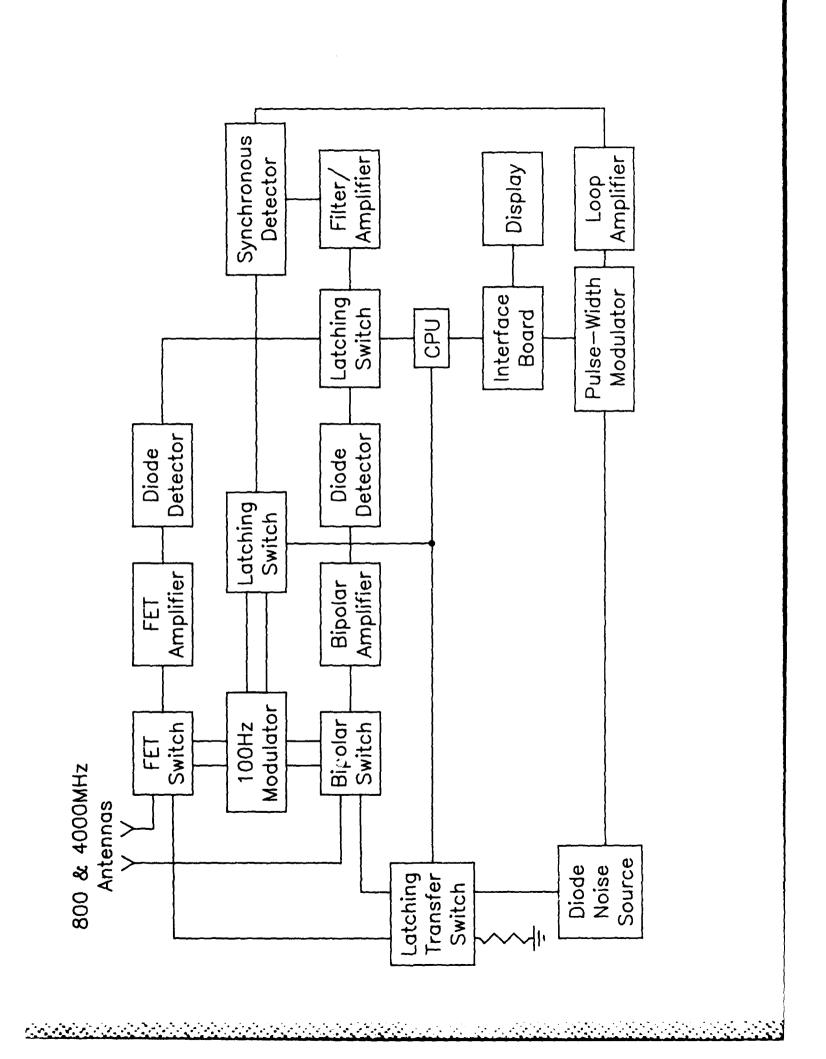


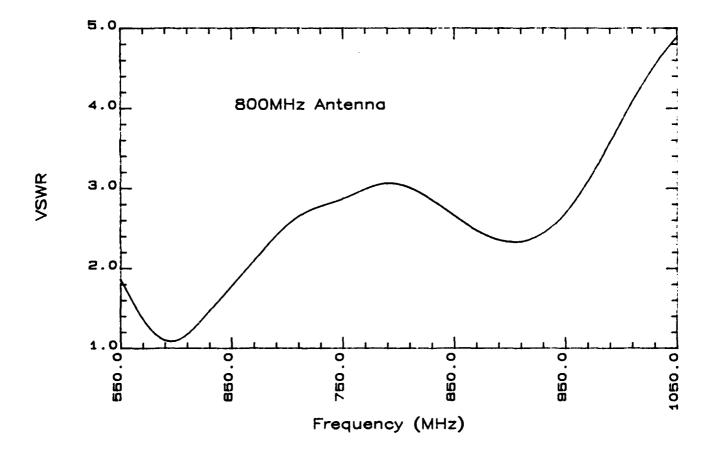


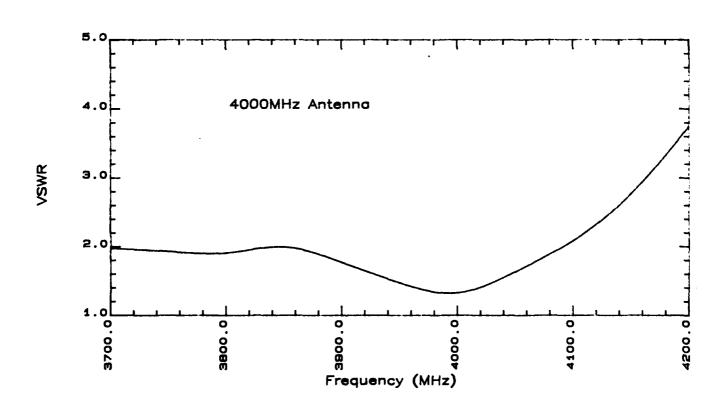


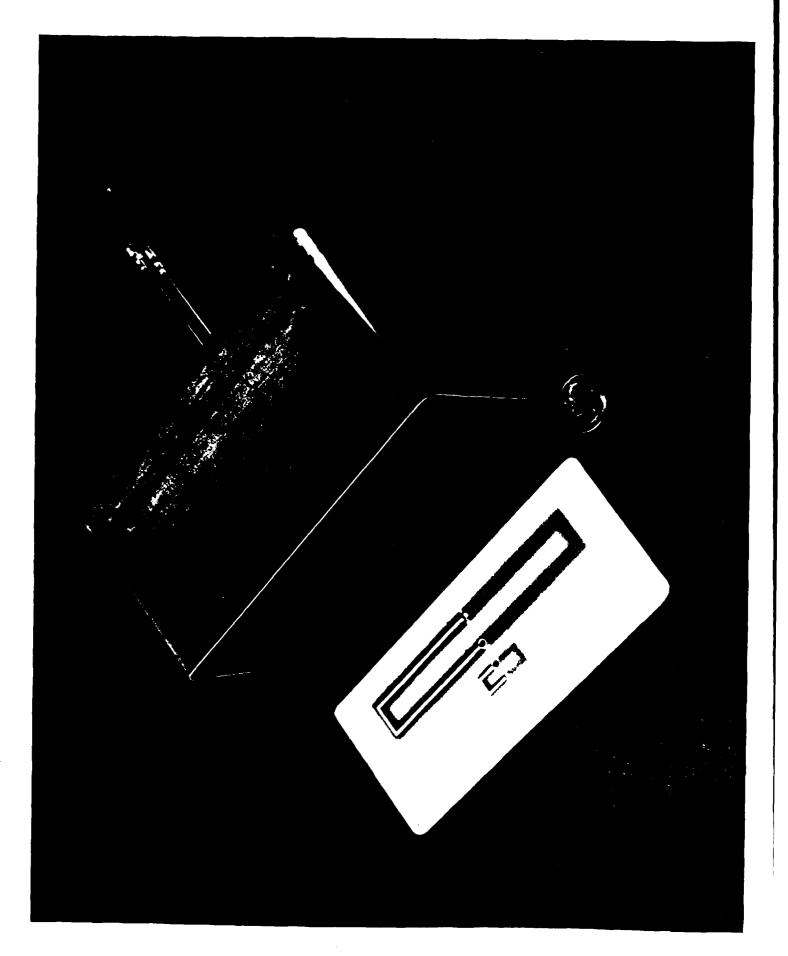


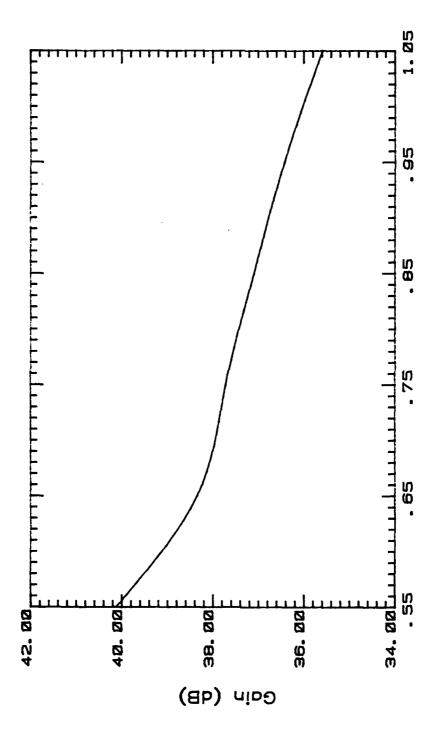




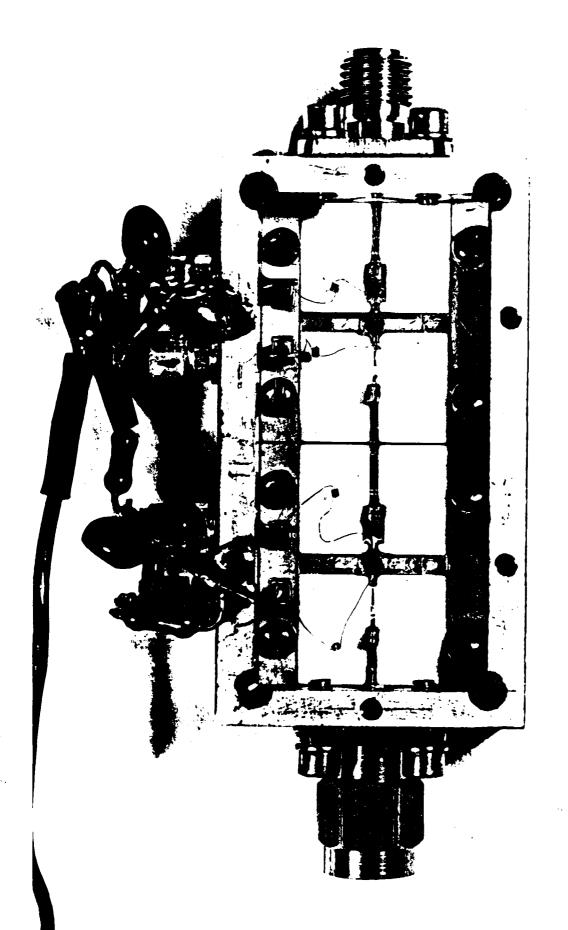


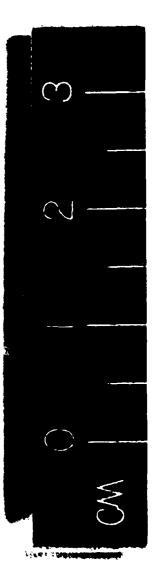


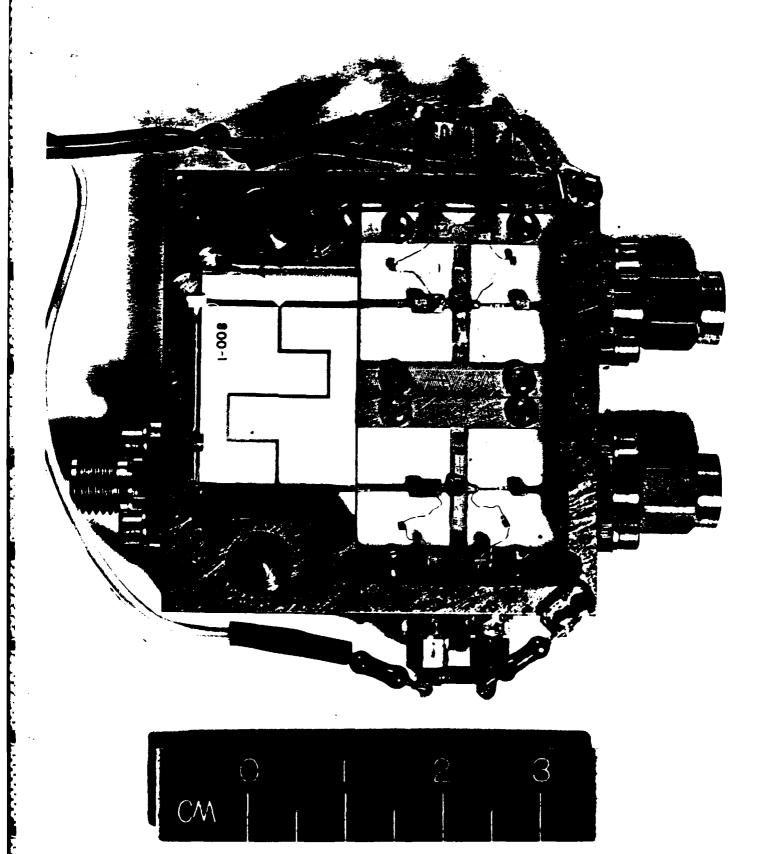


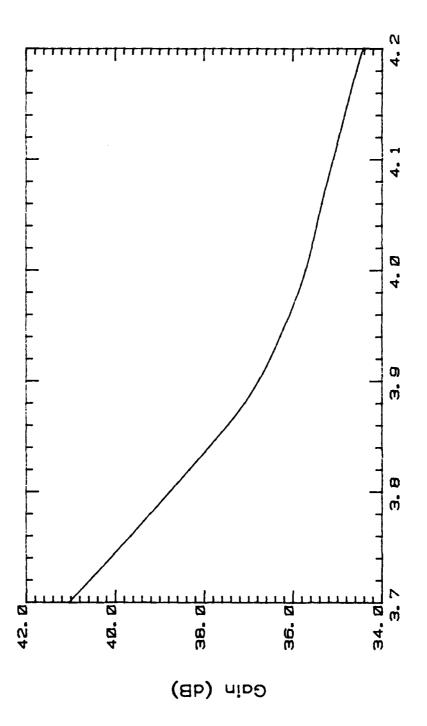


Freq.(GHz)

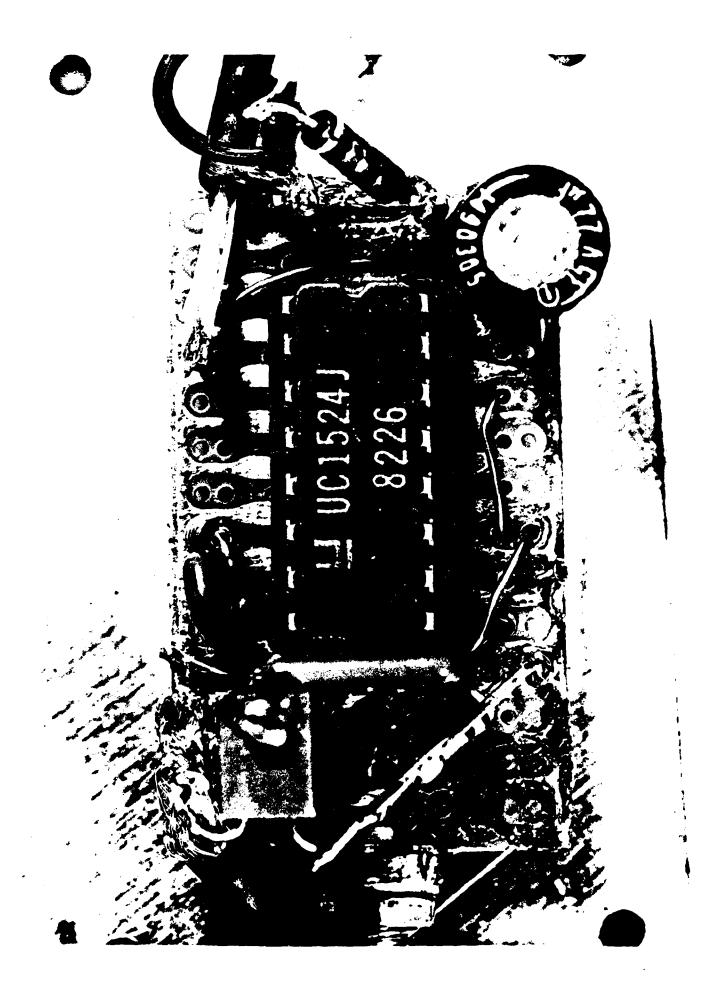


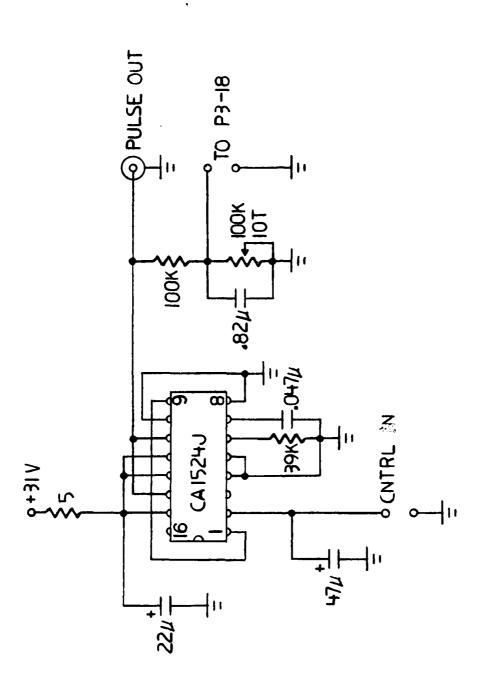


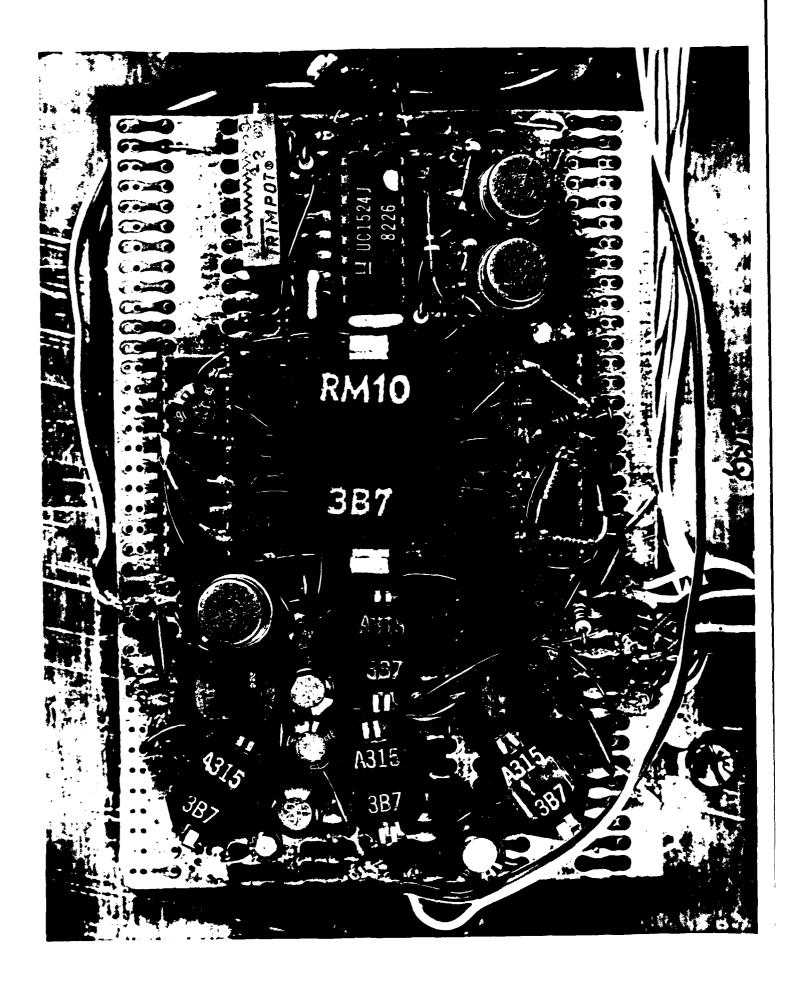


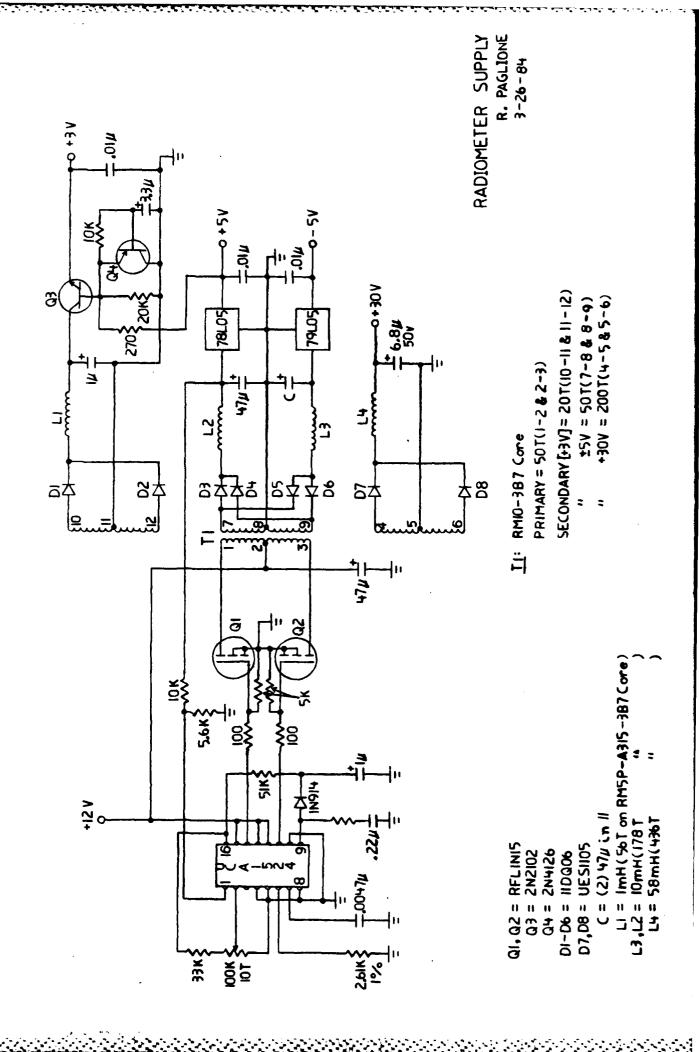


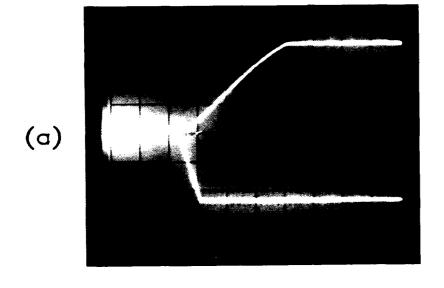
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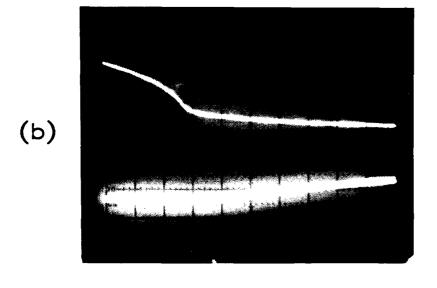


drain voitage (1v/div)

turn-on

gate voitage
(2v/div)

time scale=20msec/div

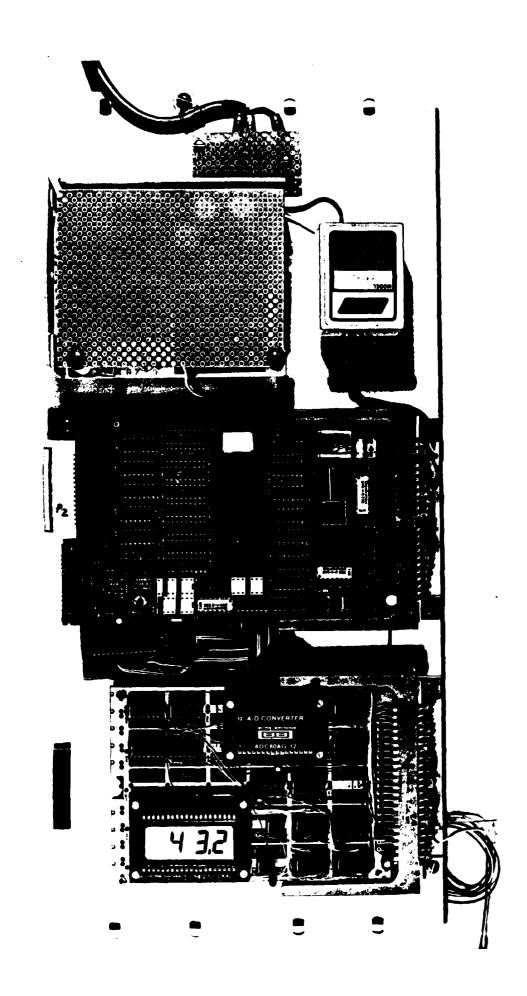


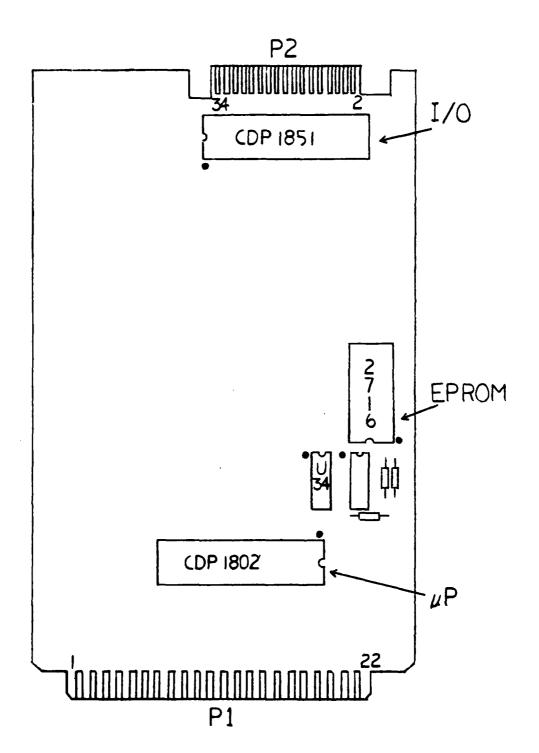
drain voltage
(1v/div)

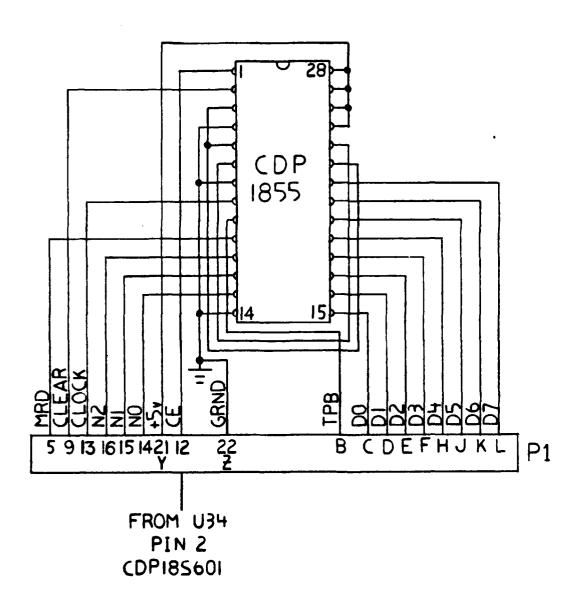
turn-off

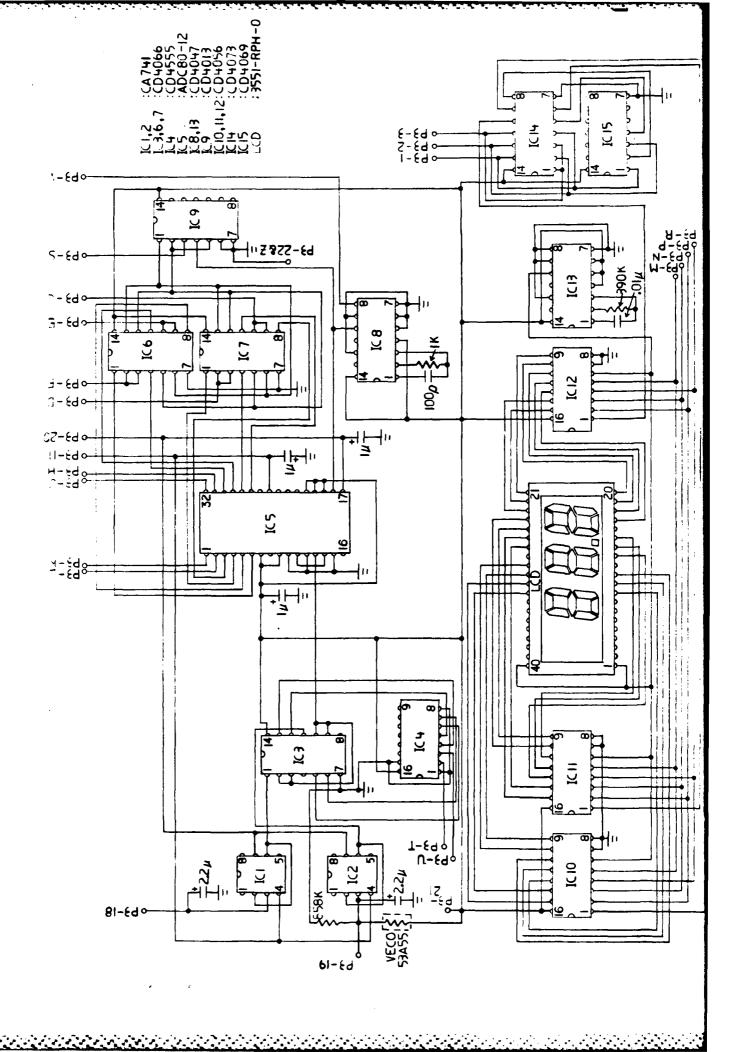
gate voltage
(2v/div)

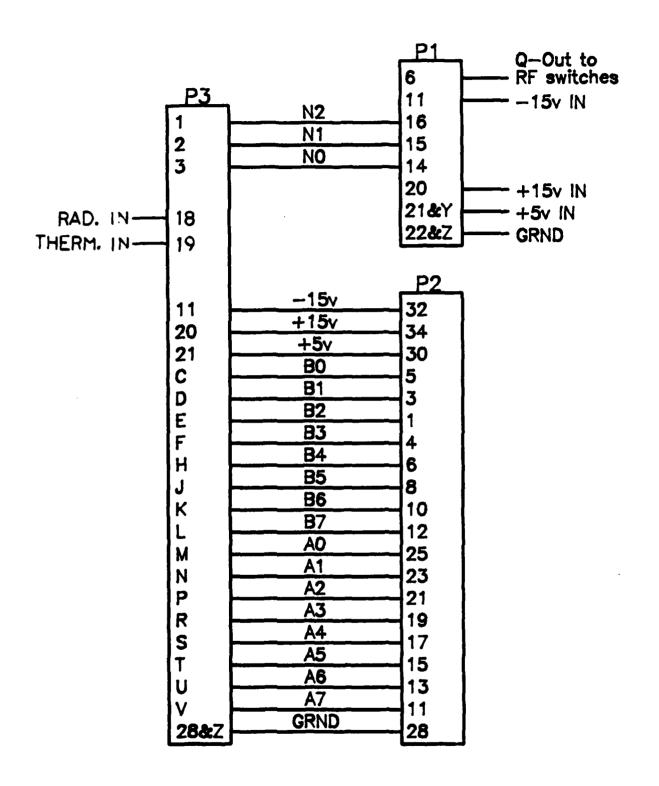
time scale=2msec/div

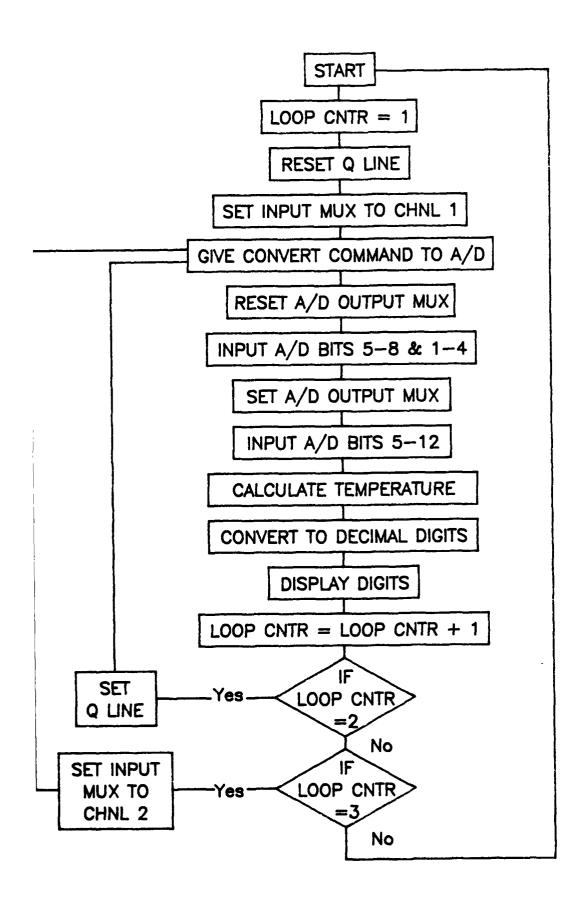


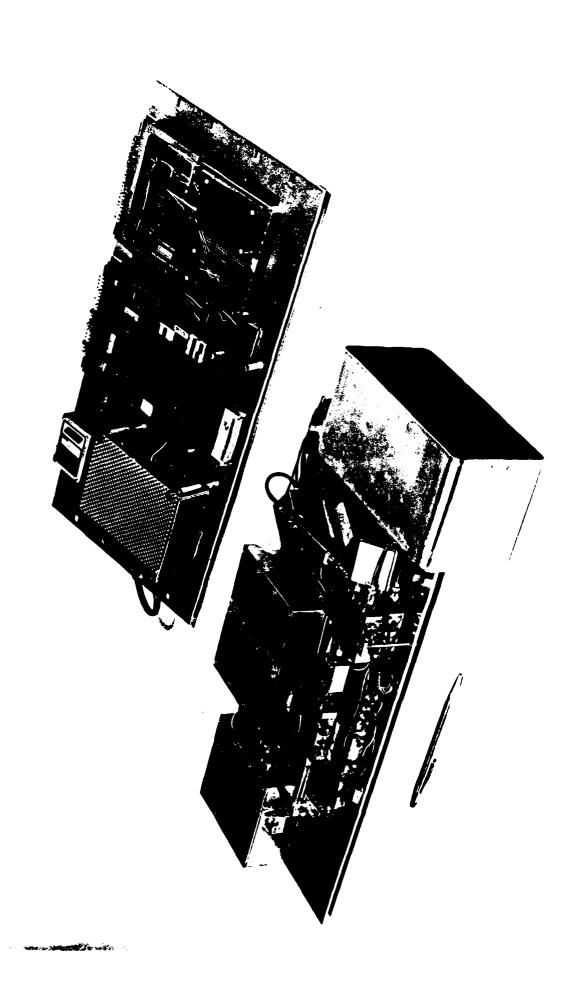


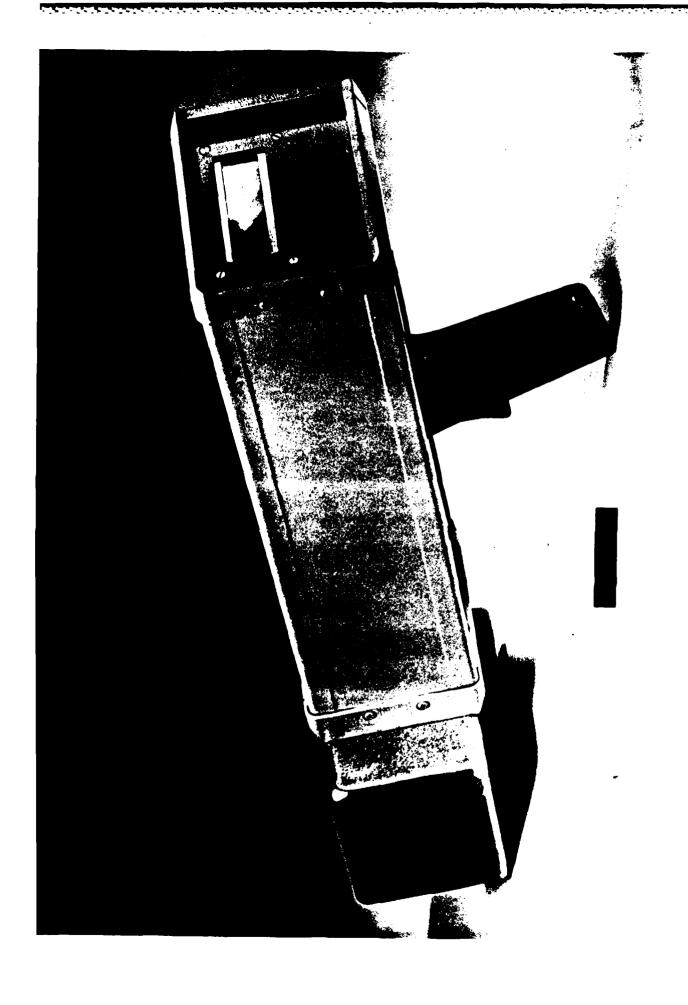












- and -5v DC supplies in the switching regulator.
- 1. 31. Photograph of the digital processor subsystem.
- 1. 32. Layout of the major components on the CDP18S601 card.
- 1. 33. Wiring diagram for the CDP1855 multiply/divide unit.
- 1. 34. Schematic diagram for the interface and display card.
- j. 35. Interconnection diagram for the card-edge connectors in the digital processor subsystem.
- J. 36. Flow chart for the operation of the software in the digital processor subsystem.
- j. 37. Photograph of the breadboard radiometer system.
- 5. 38. Photograph of prototype unit.

END

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